

ExoMars Rover Vehicle

European Industry Day

TAS-I, Turin

29 May 2008

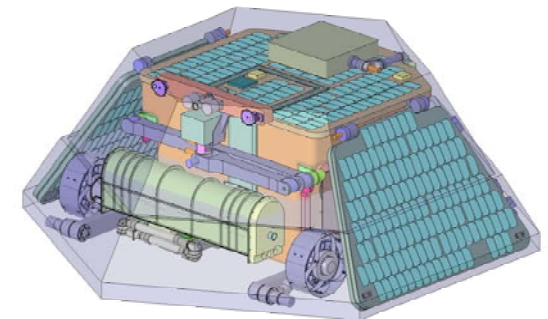
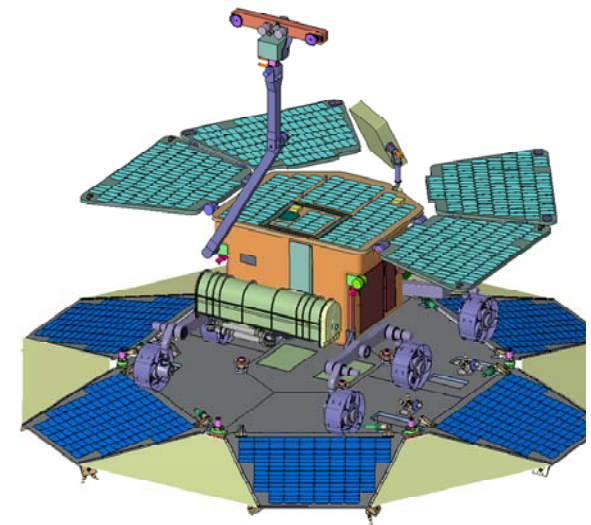
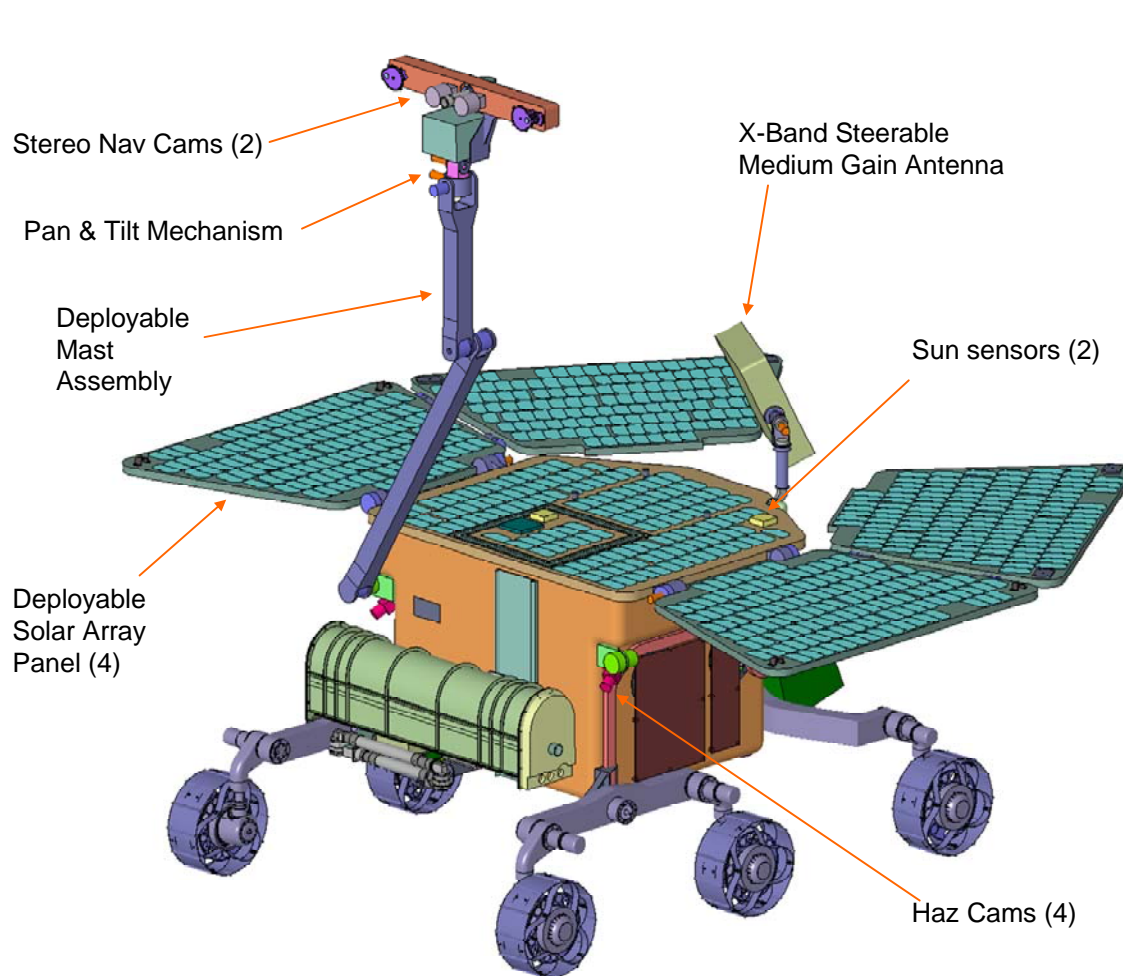
Mark Roe

Rover Vehicle Project Manager

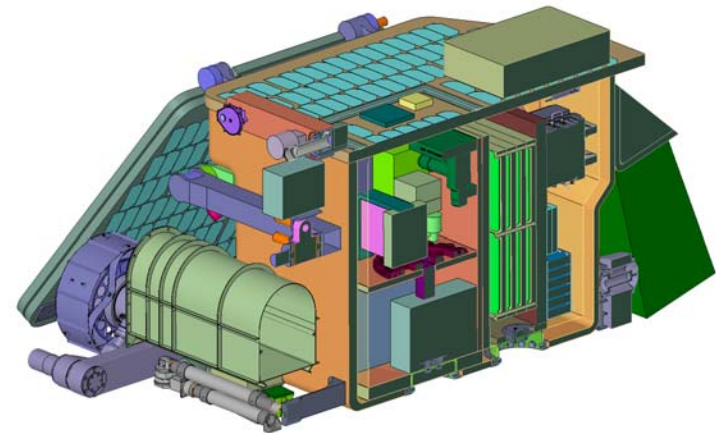
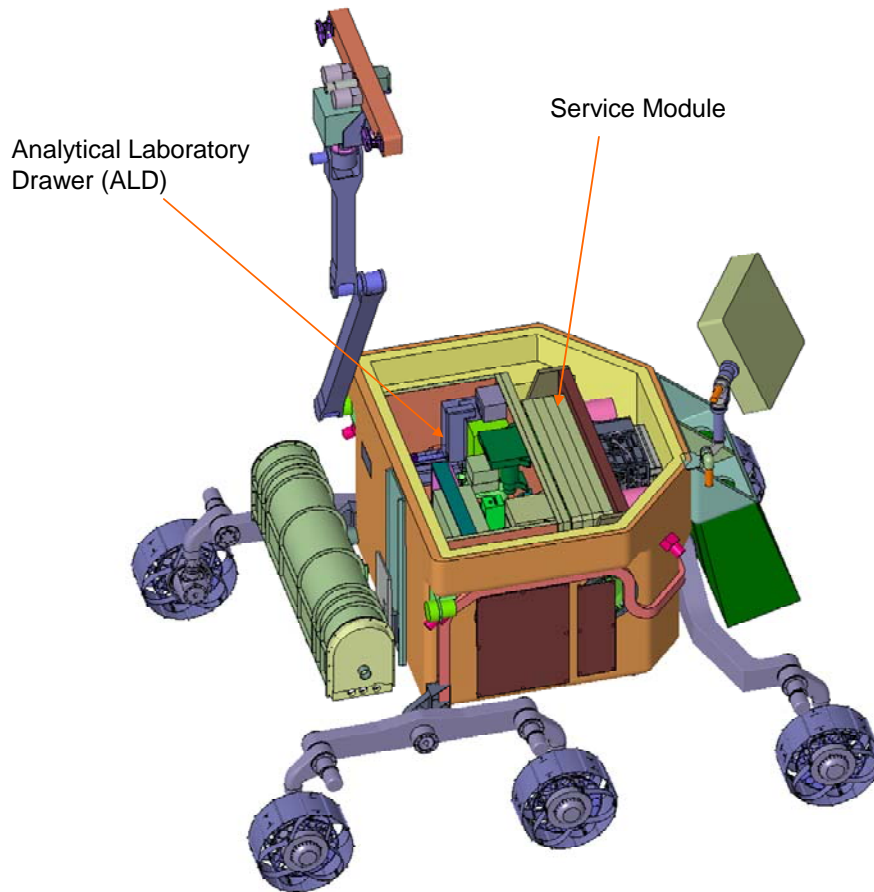
All the space you need



Rover Vehicle Configuration (1)

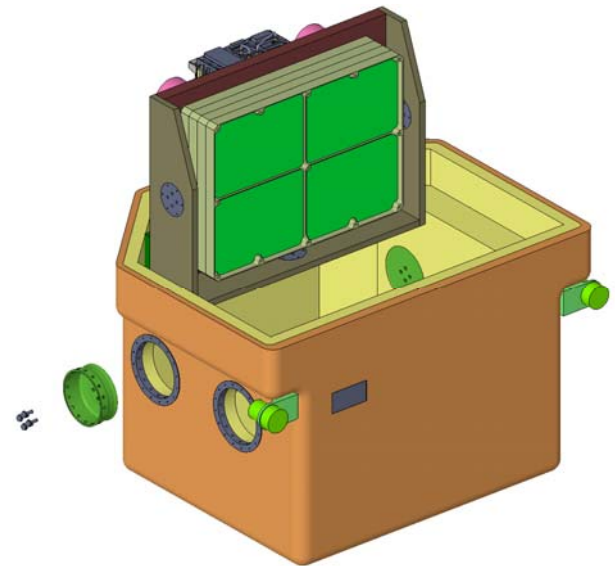
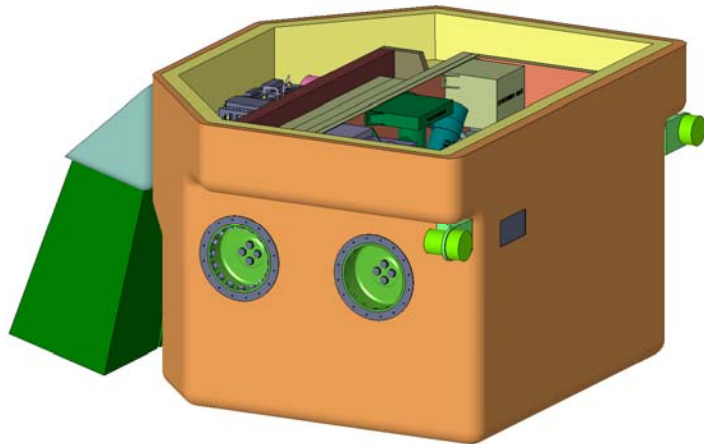


Rover Vehicle Configuration (2)

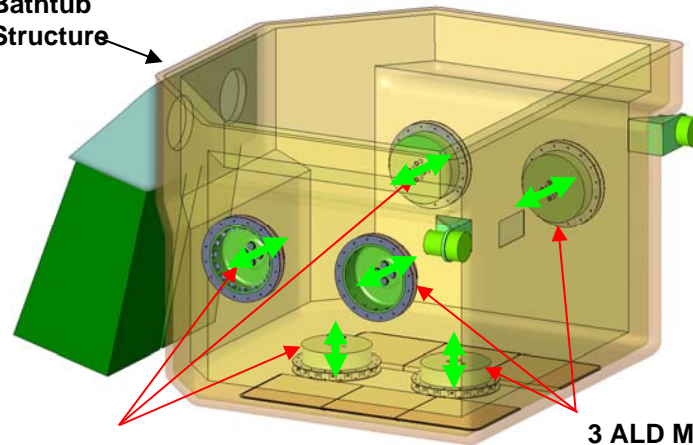


1 parties without prior written agreement. Its content shall not be disclosed.

Body Structure



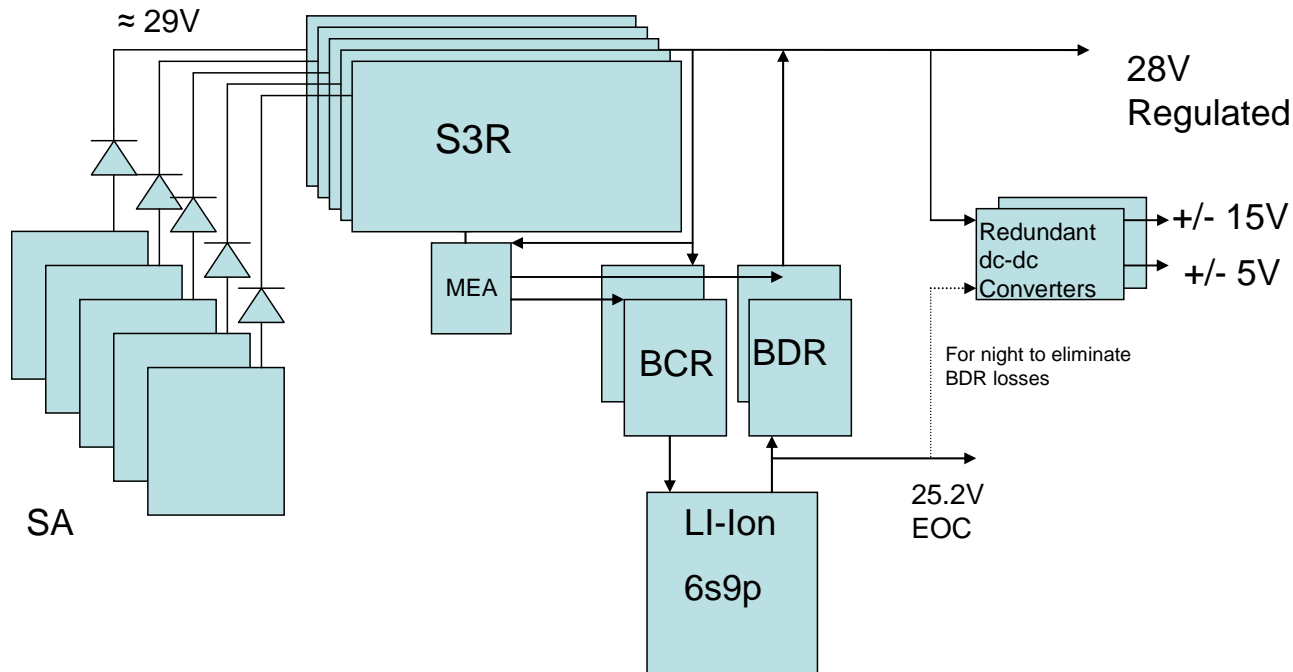
Bathtub
Structure



3 SVM
Mounts

3 ALD Mounts

Power Sub-system Architecture



■ Battery

- li-Ion
- Direct Negotiation

■ Solar array

- 2.6m2 total area
- Total of 5 panels
- 300watts

■ PCDE

- Direct Energy Transfer
- LCL's 20+20

Communications Architecture

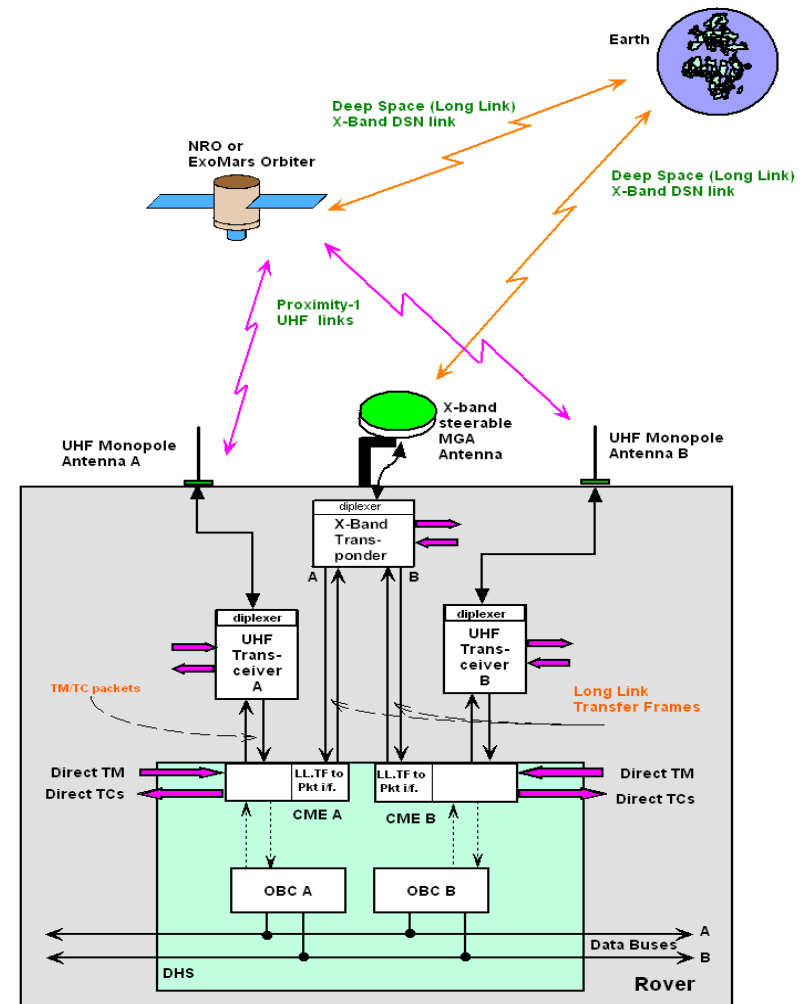


■ UHF

- Redundant UHF Transceiver
- Redundant RF Path
- Proximity-1 standard
- 2 Monopole UHF antennae
- Transceiver ITT released May08

■ X band

- Single MGA on 2-axis APM
- Single rf chain
- Transceiver



Onboard computer



■ Processor module

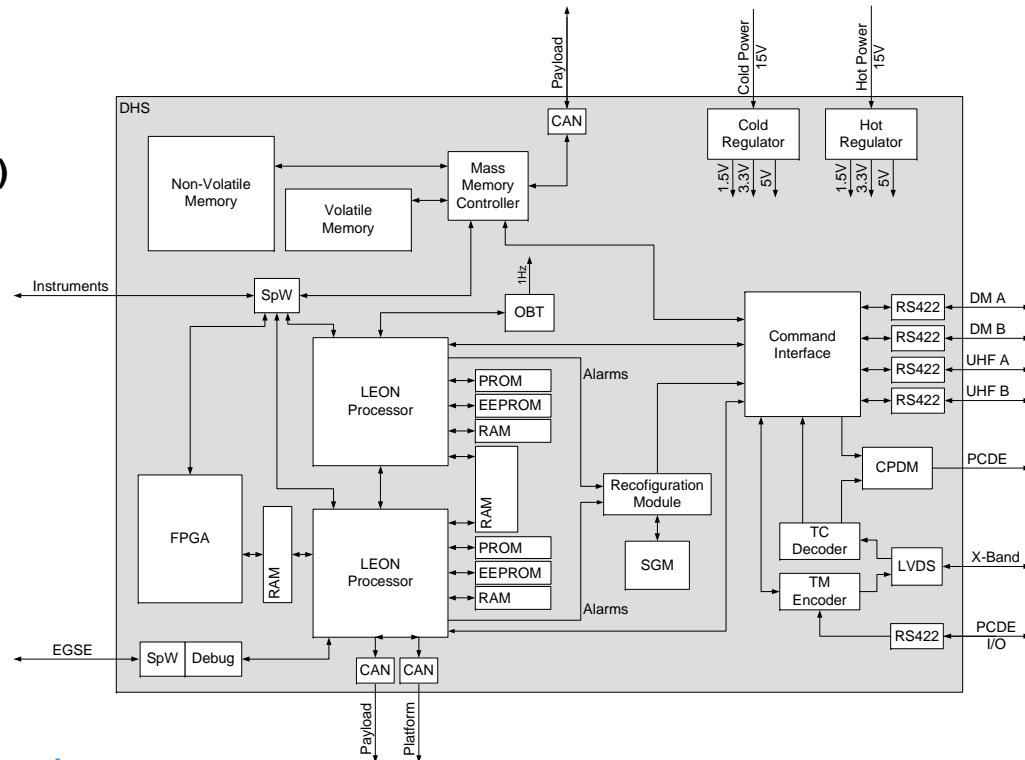
- LEON based processor(s)
- FPGA based algorithm co-processor(s)
- SpW for high speed instruments
- CAN, RS 422 data bus
- RTEMS & TBD SOIS services
- Hardware “Co-processing”

■ Mass Memory Electronics

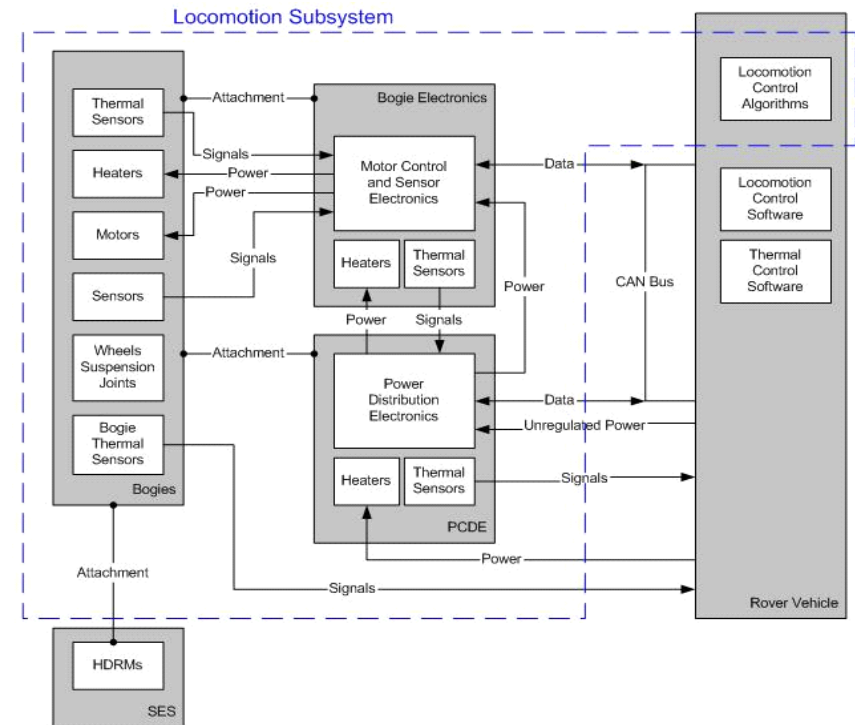
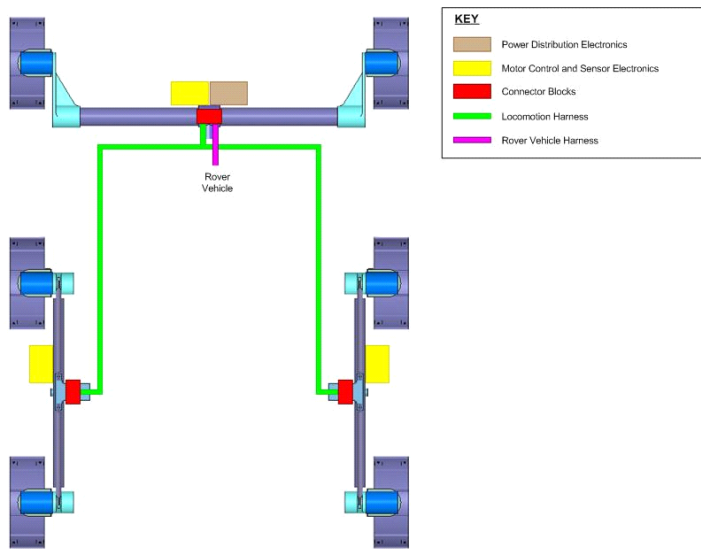
- Predominantly non-volatile
- Multiple software images
- Volatile for temp instru. data storage
- Partitioned for FAT file mgmt. sys
- Data storage as files or packets
- CAN & SpW i/fs
- EDAC protection

■ Command and Monitoring Electronics

- Transceiver interfaces & switching Telecommand decoding
- High priority telecommand to PCDE
- HKTM packet encoding
- OBC reconfiguration
- On Board Time



Locomotion Subsystem



- 6 wheel, 21 DOF system
- Includes Electronics Drive system
- Flexible wheels baselined
- *Building on existing BB activities*



Traverse and Navigation

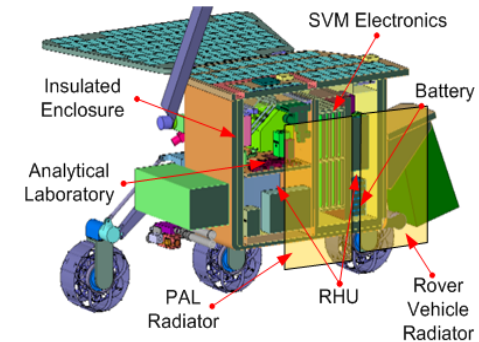
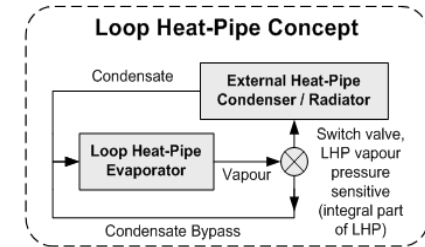
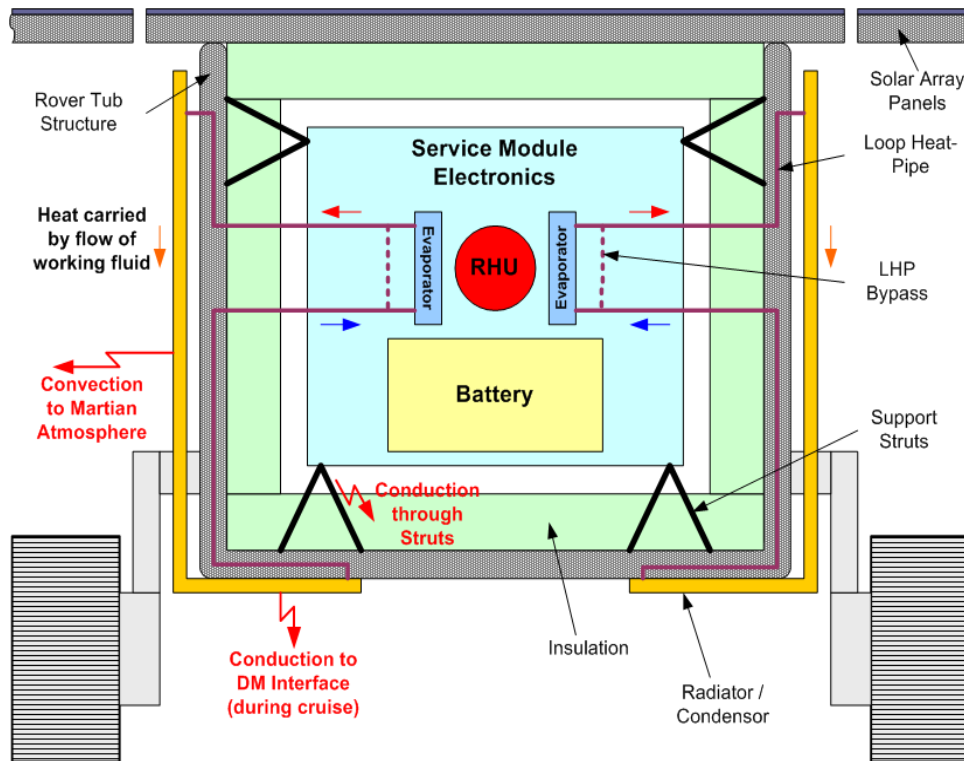


Navigation concept relies on a wide set of equipment consisting of:

- Navigation Cameras (mounted 2m above the surface at the top of the mast)
- Visual Odometry
- Inertial Measurement Unit
- Sun Sensor
- Mast and Pan & Tilt assembly



Thermal Subsystem



- Loop Heat Pipe system (~15watt)
- Standard Heater elements (mats, etc) supporting electronic control loops

Onboard SW and Operations



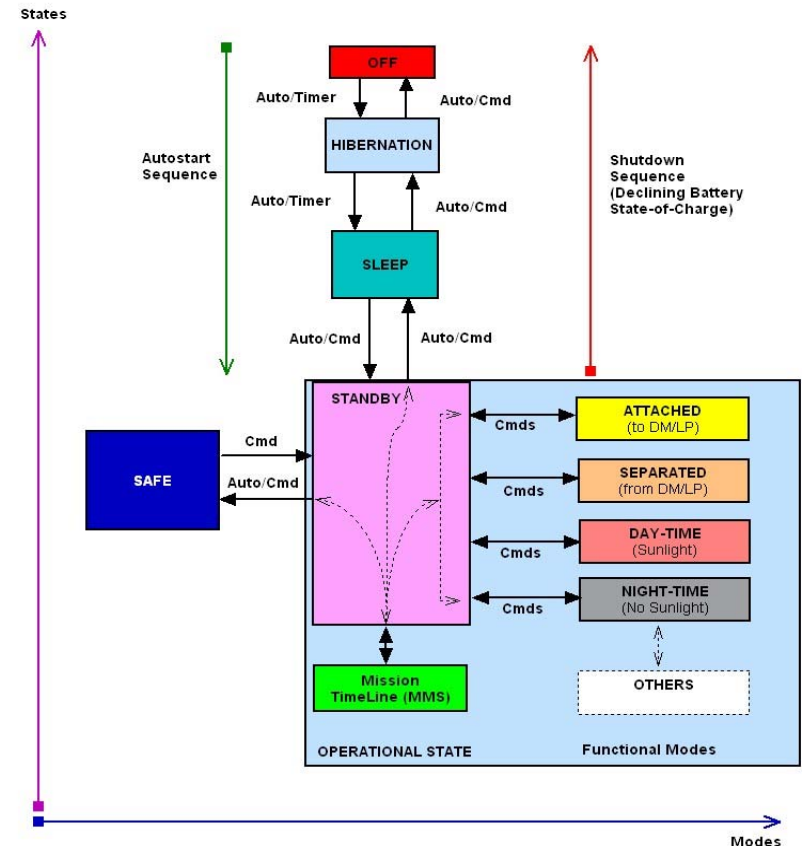
Architecture and Requirements Definition ongoing

Features:

- RTEMS OS
- Data Handling Software (providing PUS TC/TM service functionality and some architectural services)
- On-Board 'File Management' (image storage & retrieval etc)
- OBCP Interpreter
- Vehicle Application SW to perform vehicle locomotion control, localisation data processing, 'platform level' management (thermal, power etc)
- Developed using the C language
- ECSS standards

Software subcontracting

- To be released as 3-4 separate Subcontracts
- Co-engineering of solution
- Will combine several functions
- Sub-Contracting at Code level
- subcontractor will be responsible for the code and unit test activities
- Integration support to Astrium



Ground Support Equipment



■ MGSE

- Transport Containers (Asceptic)
- Turn-over Trolley
- Vertical Stands



■ EGSE

- Based on “Open Centre “
- Simulator Front-End Custom interface modules (Sim-FEE)
- SCOE (Power, TMTC, Comms)



RV Schedule challenges



■ Schedule driven by

- Launch window (~2years cycle)
- Integration sequence complexity (PP, CCC etc)
- *Necessary* model Philosophy

Jun 2009...	Development models & GNC benches
Jun 2010	Qualification Models
Oct 2010	Flight Models

RV Procurement Schedule



Product	Procurement	ITT Release
Locomotion SS	RC (Oerlikon/MDA)	Feb-08
Instrument Arm	OC	Jun-08
UHF Transceiver	OC	Apr-08
X-Band Transceiver	OC	May-08
OBC	OC	Jun-08
PCDE	OC	Jun-08
IMU	OC	Jun-08
Deployable Mast Ass	OC	Jul-08
Rover Body Structure	OC	Sep-08
X-Band Antenna	OC	Jul-08
S/A Assembly	OC	Jul-08
MDE (Option)	OC	Aug-08
Sol Array Hinges	OC	Aug-08
Battery	DN (ABSL)	Sep-08
Radiators + LHP	OC	Sep-08
RAT	OC	Oct-08
Camera System	OC	Oct-08
Sun Sensor	OC	Jan-09
MGSE (Various)	OC	1H-09
EGSE		
SCOE-Power	OC	1Q-09
SCOE-TM/TC	OC	1Q-09
SimFEE	OC	1H-09
Software		
SW Group #1	OC	Q4-08
SW Group #2	OC	1H-09
SW Group #3	OC	1H-09

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